

# Photometric Redshifts for Euclid

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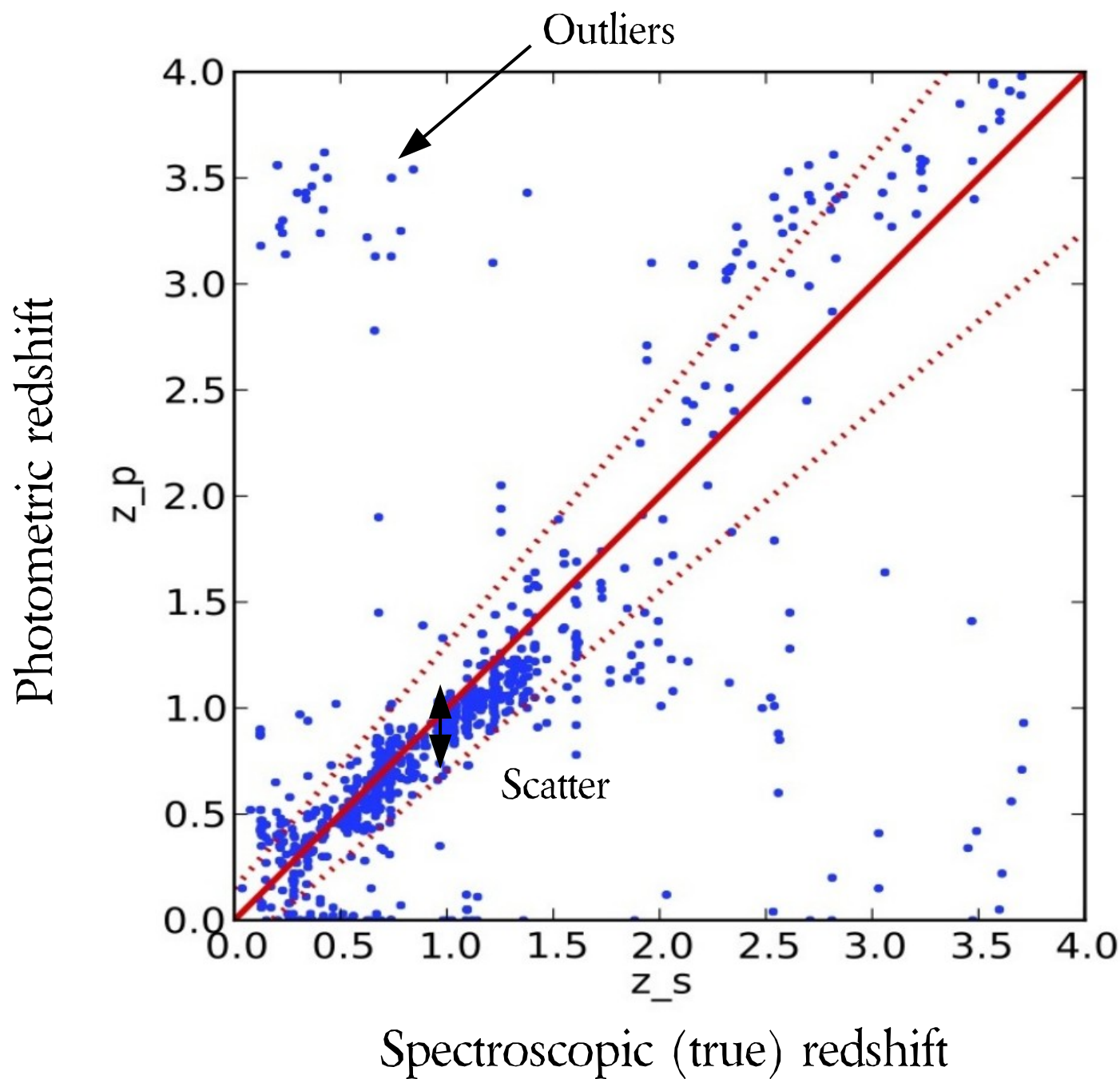
With 75 more people from OU-PHZ and CH-SDC



**UNIVERSITÉ  
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Département d'astronomie

# Euclid photo-z requirements



Euclid requirements :

Scatter :  $\sigma_z < 0.05(1+z)$

Outlier fraction : < 10 %  
beyond  $0.15(1+z)$

Bias: knowledge of  $\bar{z}$  in  
any tomographic bin  
better than  $0.002(1+z)$

# Photo-z additional requirements



- For each object in the WL sample, **provide the PDF of the redshift**
- Perform star/galaxy(/QSO) separation
- Provide (observed) SEDs of the stars (for PSF determination). What about galaxies?
- Plus a whole lot of legacy science requirements

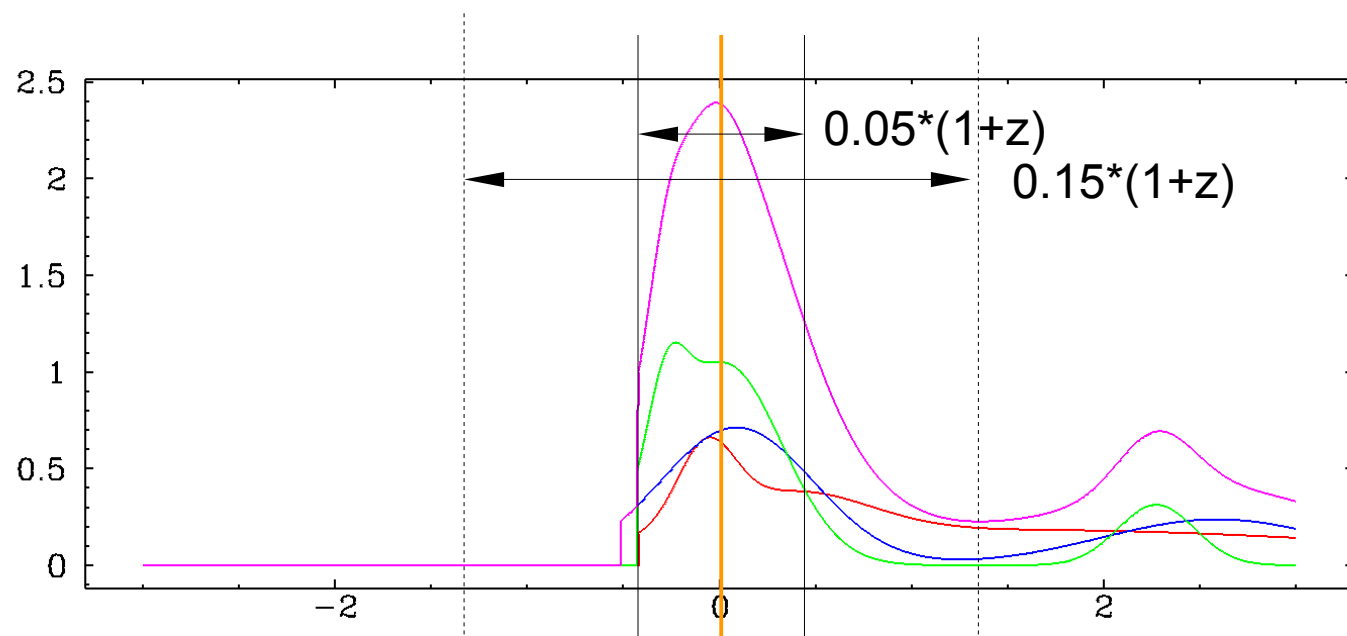
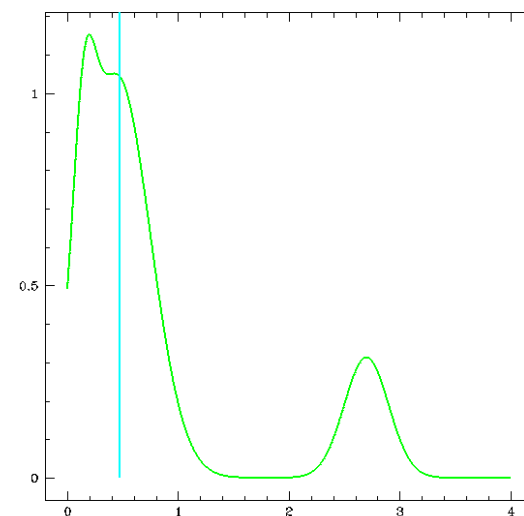
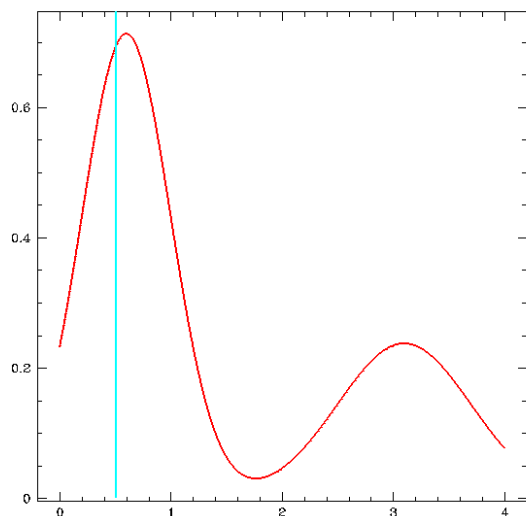
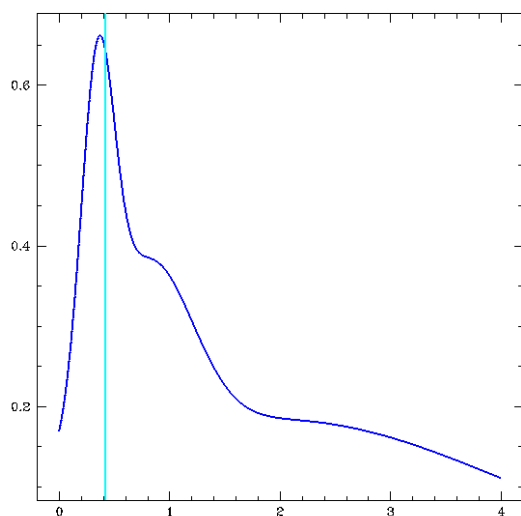
# Photo-z requirement based on PDF



In each subset (bin) used for the weak-lensing analysis, the average of the true\_z-subtracted PDF(z) (PDF(z-true\_z)) shall meet the following cumulative probability requirements:

Within $\text{ABS}(z - \text{true\_}z)/(1+z)$	Fraction of probability
0.05	68%
0.15	90%

# Photo-z requirement based on PDF

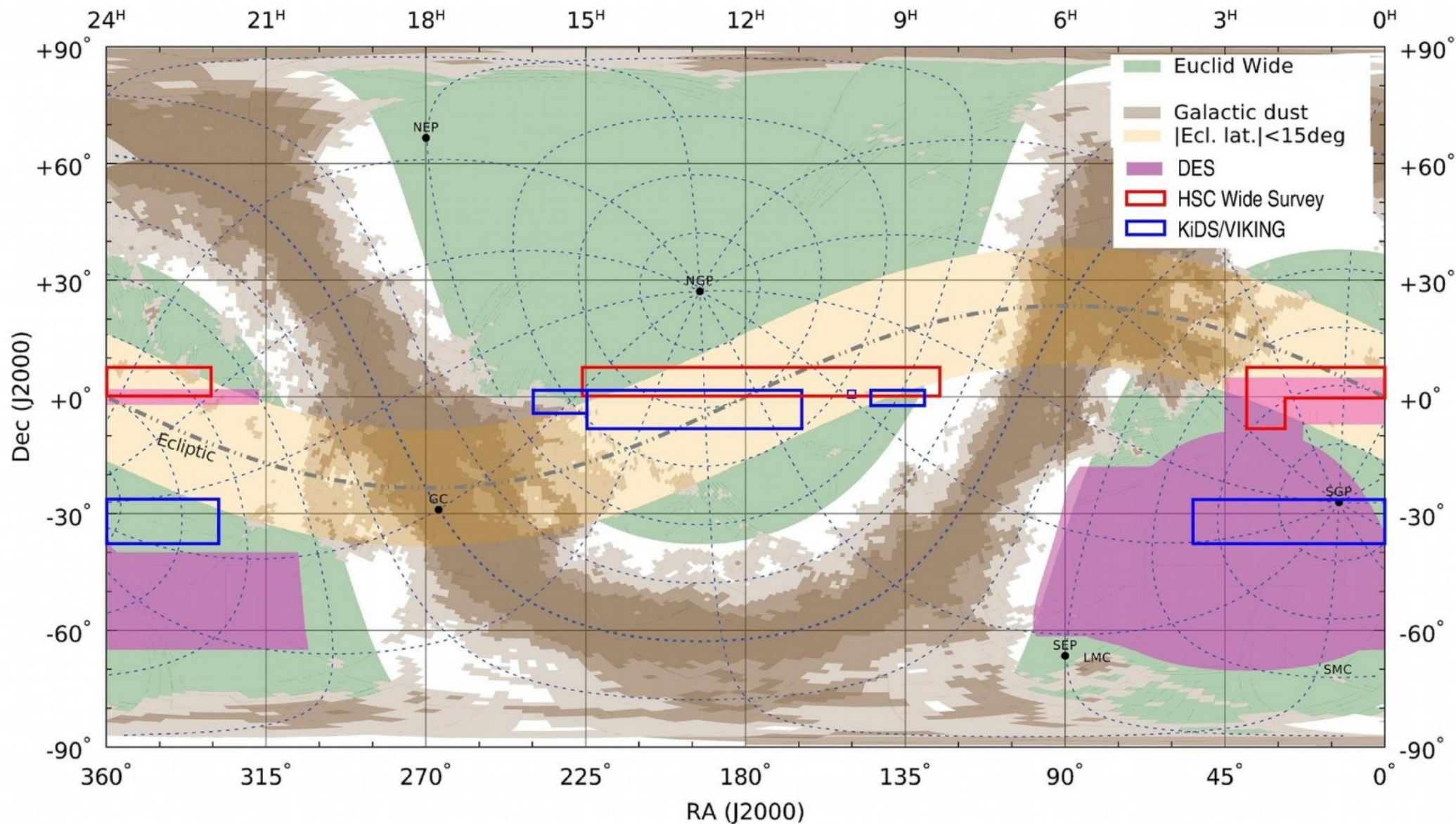


: 68 %

: 90 %

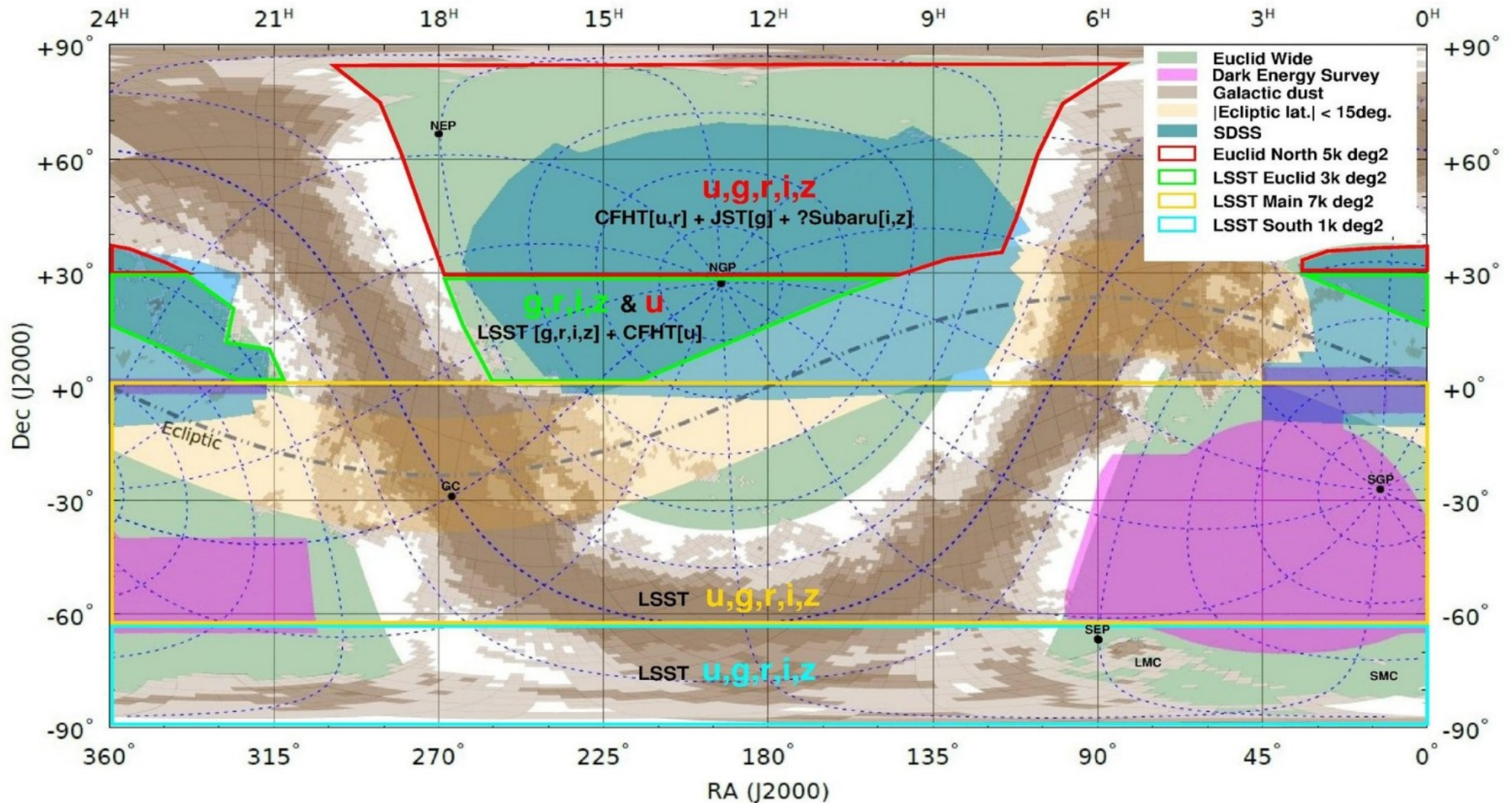


# The Euclid wide survey





# Optical ground-based data



# Calibration fields



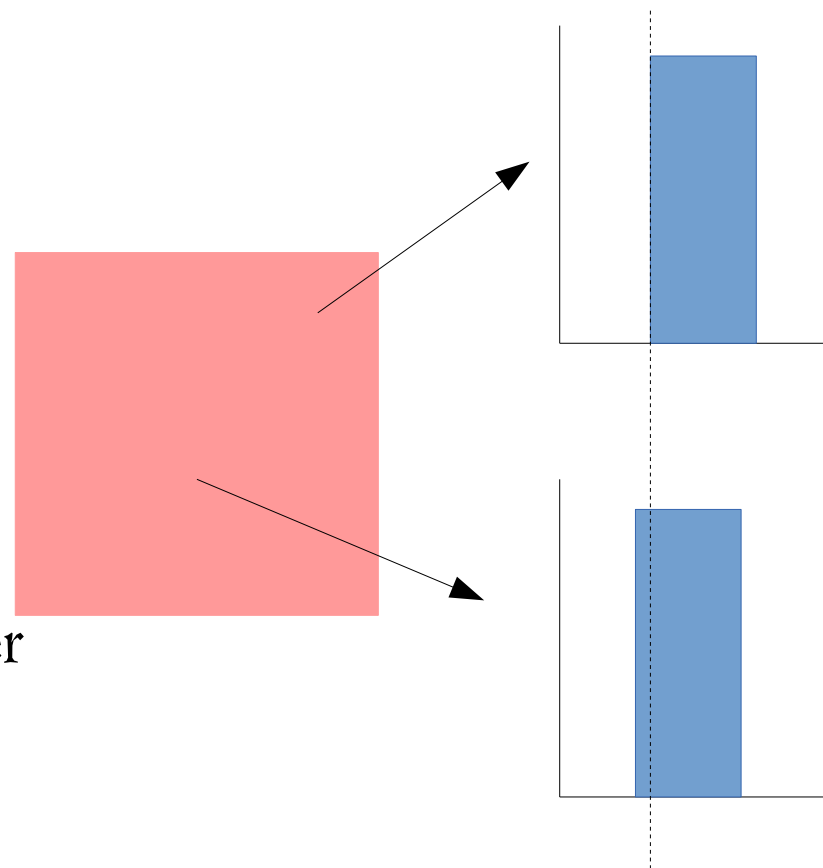
- Not the Euclid Deep Fields!
- 4  $\sim 1 \text{ deg}^2$  equatorial fields: COSMOS, SXDS, VVDS 2h, E-CDFS + 2 (GOODS-N, EGS) not so equatorial
- 25x wide exposure with Euclid, but also from optical surveys (?)
- Used to study the color distribution of galaxies
- And to build the color-redshift calibration relation (Dan's talk)
- Secondary calibration using astrometric redshifts (Vivien's talk)



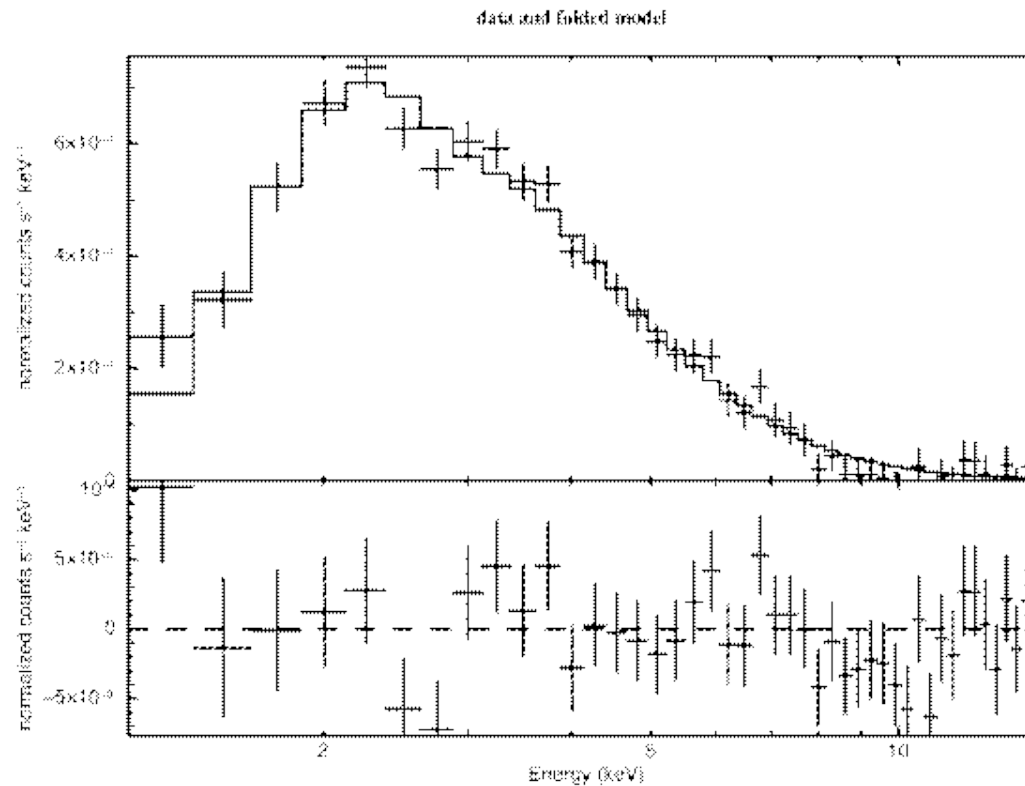
# Variable filters



- Filter transmission is location dependent
  - In the best case this introduces a scatter
  - But probably a bias, if the filter shifts in wavelength
- 
- Galactic absorption (Audrey's talk) is another source of fluctuation in the transmission
  - And actually, don't forget the atmosphere...  
but we may be unable to do anything about that...

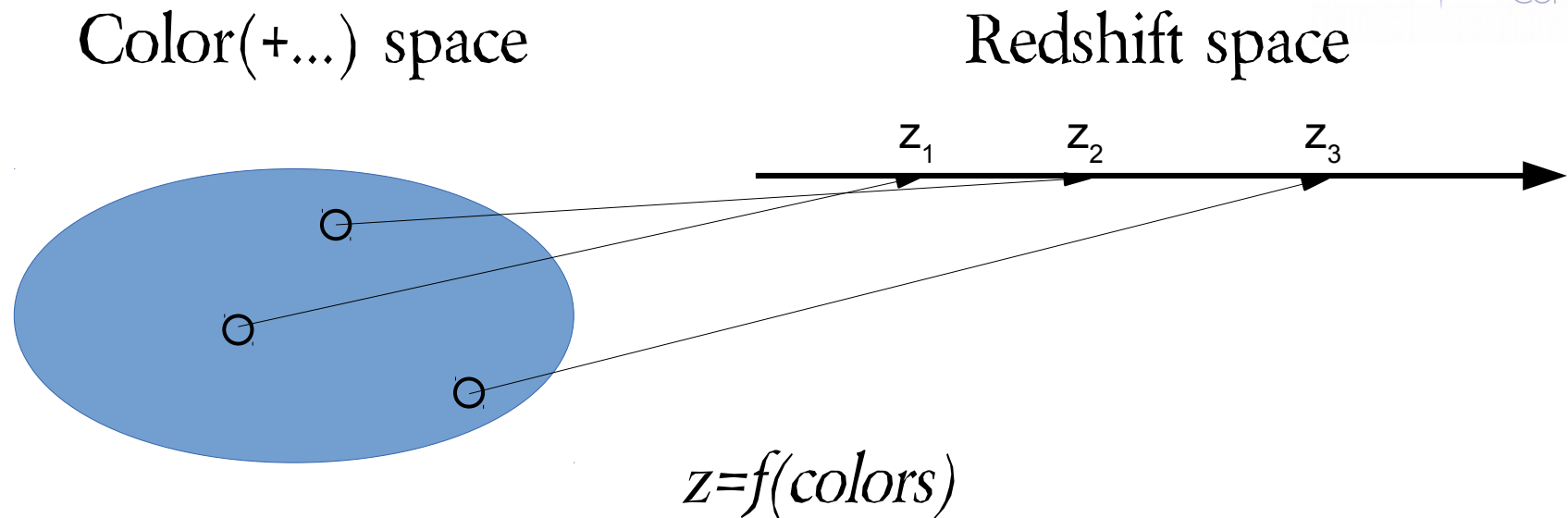


# Photometry, the X-ray way



- In X-ray astronomy, each observation comes with its own response. The source spectral properties are then obtained by forward fitting an emission model through the response to the count rates
- This can be “easily” treated with template-fitting algorithms
- Can we fix the colors for ML? (Jean's talk)

# Photometric-redshift algorithms



Mapping  $f$  can be constructed based on prior knowledge :

- Template-fitting: Hyper-Z, Le Phare, BpZ, **Phosphoros**,...

Or it can be discovered:

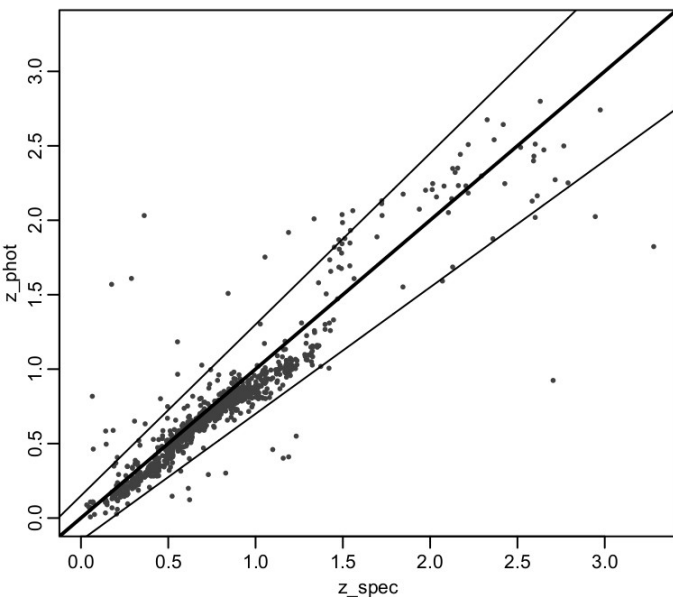
- Machine-learning: Nearest neighbors, Perceptron, Support vector regression, Random Forest, Adaboost, Gaussian Processes, ...

Both have advantages and disadvantages; we probably want to use both

# Combining TF and ML (with ML)

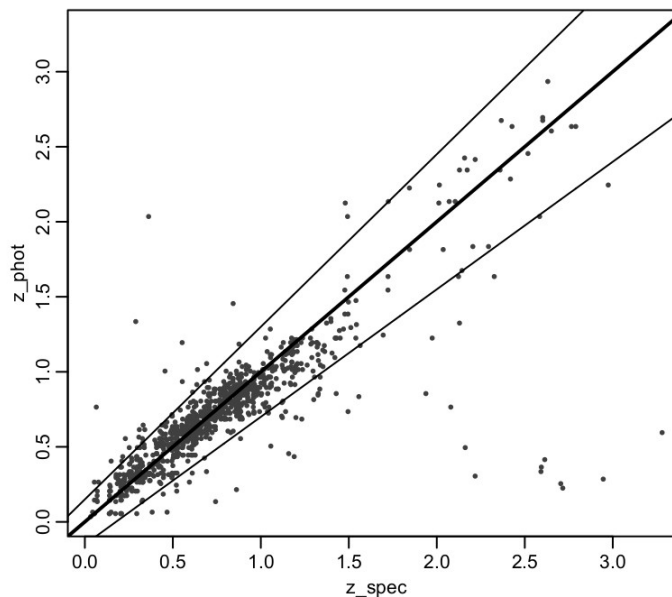


**Template fits, auto; est.: mean**  
scatter=0.06; outliers=0.038



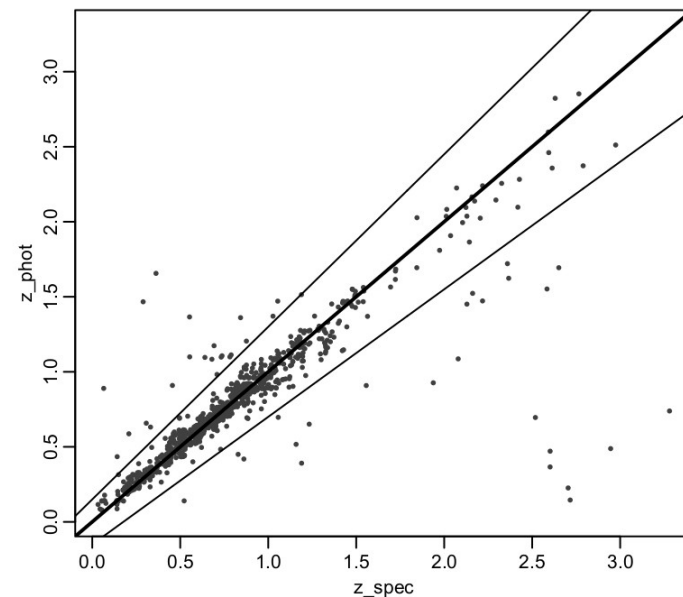
Le Phare

**OB fits, auto; est.: mode**  
scatter=0.055; outliers=0.072



TPZ

**Combination; est.: median**  
scatter=0.027; outliers=0.041



Combination

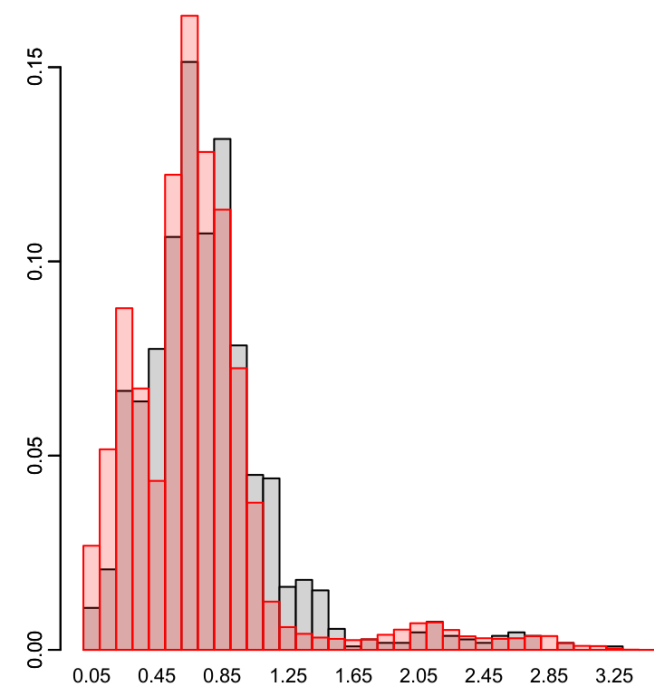
Classifier-based combination (Random Forest)



# $N(z)$ Reconstruction

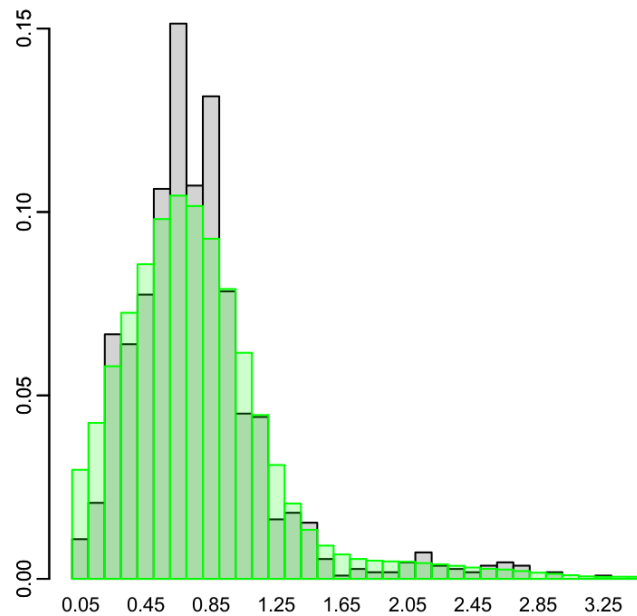


Template fit



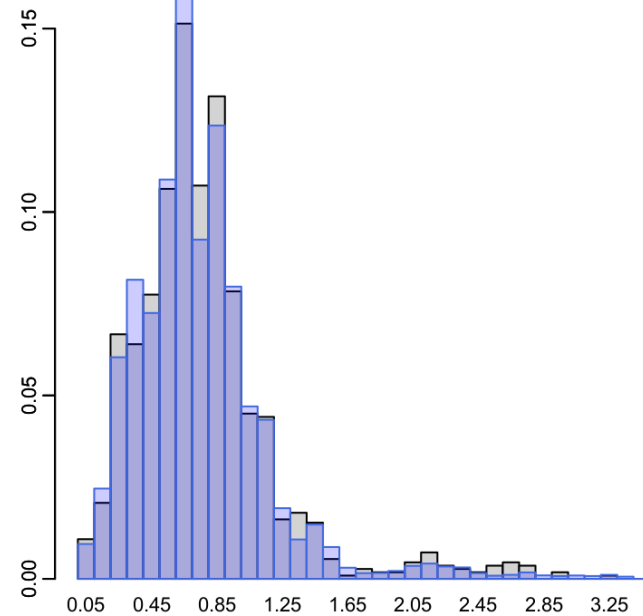
Le Phare

Overlapping bins method



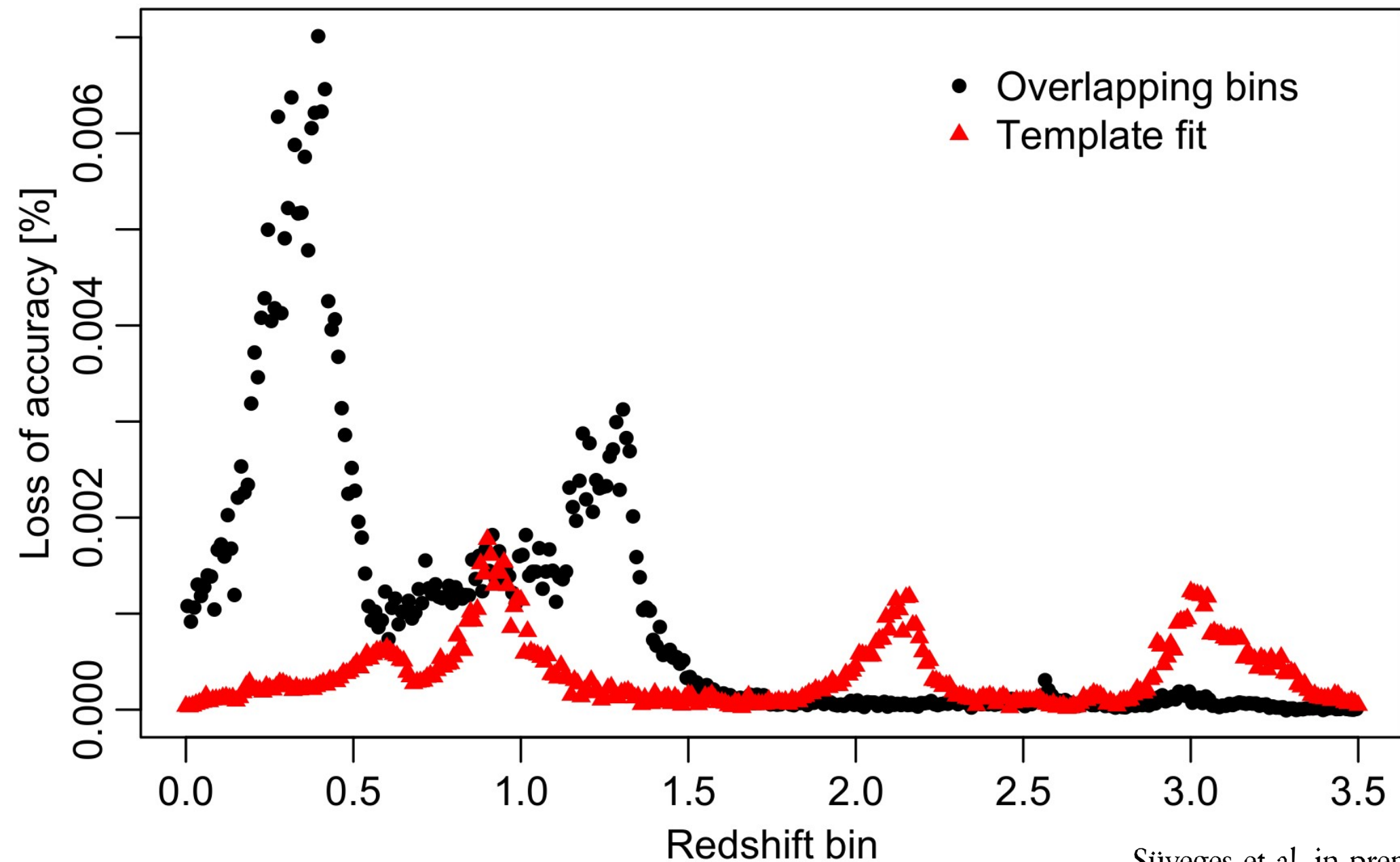
TPZ

Combination



Combination

# Feature importance



# Conclusions



- Euclid will use inhomogeneous optical survey
- Outlier fraction and scatter requirements not so hard, if one has good photometry
- But very stringent requirements on the bias
- Ready to cope with variable transmissions ??
- We are probably using more than one photo-z algorithm

# Template-Fitting Advantages



- ✓ Based on astrophysical knowledge; the better the knowledge, the better the algorithm
- ✓ Any physical process that is understood can be modeled explicitly (e.g., Galactic absorption)
- ✓ Constructs naturally a likelihood, and can be turned into a fully Bayesian approach
- ✓ Can cope with informative priors in a very natural way, e.g. luminosity function, cosmological volume



# Template-Fitting Disadvantages



- ✗ Knowledge of the sky is imperfect (wrong templates) and incomplete (lack of templates)
- ✗ No clear guidelines on the number of templates (not a continuous quantity)
- ✗ Computationally intensive
- ✗ Cannot easily cope with additional features (galaxy shape, etc. ; but is it useful ?)
- ✗ Link between photometry and galaxy properties not so clear (e.g., aperture effects)

# Machine-Learning Advantages



- ✓ No need to understand the astrophysics or to model any physical process
- ✓ Can easily incorporate additional features, e.g., different types of photometry; good ML algorithms can do it without loss of stability
- ✓ A sound ML algorithm will be optimal where training set is “good”
- ✓ Not linked to galaxy properties, so photometry does not really matter

# Machine-Learning Limitations



- ✗ Many algorithms cannot produce naturally a PDF
- ✗ There are “hidden priors” in the selection of the training set
- ✗ The training set must be “good” whatever that means
- ✗ There might be over- or under-fitting if the model complexity is not chosen properly
- ✗ Extrapolations might/will occur if the training set is incomplete

# But is ML better ?



- Results depend strongly on the quality of the training set
- Training set and test set generally come from the same population
  - Meaningful comparison must at least use a weighting scheme (e.g., Lima et al. 2008)
  - Any missing population will probably be better characterized with template-fitting
- Template-fitting involves some “black magic”, so the result depends a lot on fine tuning